

A Framework for Classifying Cocyclic HMs of Order $8p$

Santiago Barrera Acevedo

School of Mathematics
Monash University

Hadamard matrices

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(Versailles 1865 – Paris 1963)

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- Hadamard showed that such maximal determinant, $n^{n/2}$, is achieved by matrices with entries from the set $\{\pm 1\}$ if and only if they satisfy (1).
- Hadamard showed that the order of a HM is necessarily 1, 2 or $4n$ for $n \in \mathbb{N}$.



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Equivalence of Hadamard matrices

- A driving force behind HM research is the **Hadamard Conjecture**, which asserts that for every positive integer n there exists a HM of order $4n$.[‡]

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- Since the number of HMs of order $4n$ appears to grow rapidly with n (which contrasts with the Hadamard Conjecture), it is necessary to introduce an equivalence relation on the set of HMs.

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- Two HMs H and H' are **equivalent** if they lie in the same $\mathbf{Mon}(n, \{\pm 1\})$ -orbit.

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Classification of Hadamard matrices

- The classification of HMs of orders less than 30, up to equivalence, was achieved through the efforts of numerous mathematicians in the 1980s and 1990s[†]

n	1	2	3	4	5	6	7
# classes	1	1	1	5	3	60	487

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- The classification of HMs of order 32, up to equivalence, was achieved in 2012.[‡]

Hadamard Matrices of Order 32

Hadi Kharaghani¹ and Behruz Tayfeh-Rezaie²

¹Department of Mathematics and Computer Science, University of Lethbridge, Lethbridge, Alberta T1K3M4, Canada, E-mail: kharaghani@uleth.ca

²School of Mathematics, Institute for Research in Fundamental Sciences (IPM), P.O. Box 19395-5746, Tehran, Iran

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Abstract: Two Hadamard matrices are considered equivalent if one is obtained from the other by a sequence of operations involving row or column permutations or negations. We complete the classification of Hadamard matrices of order 32. It turns out that there are exactly 13,710,027 such matrices up to equivalence. © 2012 Wiley Periodicals, Inc. *J. Combin. Design* 21: 212–221, 2013

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- The classification of HMs of order 32, up to equivalence, was achieved in 2012.[‡]
- There are exactly **13,710,027** equivalence classes of HMs.
- Given the profusion of equivalence classes of HMs, even at small orders, it makes sense to ask for classifications of HMs of special types.

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Cocyclic Development of Designs

K.J. HORADAM AND W. DE LAUNEY

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Abstract. We present the basic theory of cocyclic development of designs, in which group development over a finite group G is modified by the action of a cocycle defined on $G \times G$. Negacyclic and ω -cyclic development are both special cases of cocyclic development.

Techniques of design construction using the group ring, arising from difference set methods, also apply to cocyclic designs. Important classes of Hadamard matrices and generalized weighing matrices are cocyclic.

We derive a characterization of cocyclic development which allows us to generate all matrices which are cocyclic over G . Any cocyclic matrix is equivalent to one obtained by entrywise action of an asymmetric matrix and a symmetric matrix on a G -developed matrix. The symmetric matrix is a Kronecker product of two ω -cyclic matrices, and the asymmetric matrix is determined by the second integral homology group of G .

We believe this link between combinatorial design theory and low-dimensional group cohomology leads to (i) a new way to generate combinatorial designs; (ii) a better understanding of the structure of some known designs; and (iii) a better understanding of known construction techniques.

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We believe this link between combinatorial design theory and low-dimensional group cohomology leads to (i) a new way to generate combinatorial designs; (ii) a better understanding of the structure of some known designs; and (iii) a better understanding of known construction techniques.

- Let G be a finite group and let A be a $\mathbb{Z}G$ -module. A 2-cocycle[‡] (or simply cocycle) with coefficients in A is a map

$\psi : G \times G \rightarrow A$ such that

$$\psi(g, h)\psi(gh, k) = \psi(h, k)^g \psi(g, hk), \text{ for all } g, h, k \in G. \quad (3)$$

[‡]Up to equivalence of extensions, central extensions of A by G can be parameterised by the group $Z(G, A) = \{\psi : G \times G \rightarrow A \mid \psi(g, h)\psi(gh, k) = \psi(h, k)\psi(g, hk), \text{ for all } g, h, k \in G\}$

- A **coboundary** is a cocycle of the form $\psi(g, h) = \phi(g)\phi(h)\phi(gh)^{-1}$ for a map $\phi : G \rightarrow A$.

Cocyclic Hadamard matrices

- A **coboundary** is a cocycle of the form $\psi(g, h) = \phi(g)\phi(h)\phi(gh)^{-1}$ for a map $\phi : G \rightarrow A$.
- In the following, let $A = C_2 = \langle -1 \rangle$ (with trivial $\mathbb{Z}G$ -action).

A HM H of order $4n$ is **cocyclic** with **indexing group** $G = \{g_1, \dots, g_{4n}\}$ if there exist a 2-cocycle $\psi : G \times G \rightarrow \langle -1 \rangle$ and a map $\phi : G \rightarrow \langle -1 \rangle$ such that

$$H \equiv [\psi(g_i, g_j)\phi(g_i g_j)]_{i,j} \quad (4)$$

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- Note $H \equiv [\psi(g_i, g_j)\phi(gh)\phi(g)\phi(h)]_{i,j}$; we work with this matrix instead.

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- In 2010, Ó Catháin and Röder reported the classification of CHMs of order less than 40.

The cocyclic Hadamard matrices of order less than 40

Padraig Ó Catháin · Mare Röder

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Abstract In this paper all cocyclic Hadamard matrices of order less than 40 are classified. That is, all such Hadamard matrices are explicitly constructed, up to Hadamard equivalence. This represents a significant extension and completion of work by de Launey and Ito. The theory of cocyclic development is discussed, and an algorithm for determining whether a given Hadamard matrix is cocyclic is described. Since all Hadamard matrices of order at most 28 have been classified, this algorithm suffices to classify cocyclic Hadamard matrices of order at most 28. Not even the total numbers of Hadamard matrices of orders 32 and 36 are known. Thus we use a different method to construct all cocyclic Hadamard matrices at these orders. A result of de Launey, Flannery and Horadam on the relationship between cocyclic Hadamard matrices and relative difference sets is used in the classification of cocyclic Hadamard matrices of orders 32 and 36. This is achieved through a complete enumeration and construction of $(4t, 2, 4t, 2t)$ -relative difference sets in the groups of orders 64 and 72.

Classification of Cocyclic Hadamard matrices

- In 2010, Ó Catháin and Röder reported the classification of CHMs of order less than 40.
- To achieve this, they used a known connection between CHMs and certain semi-regular $(4n, 2, 4n, 2n)$ relative difference sets in groups of order $8n$.[†]

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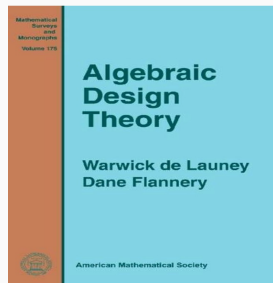
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n	1	2	3	4	5	6	7	8	9
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[†]de Launey, Flannery, and Horadam, Cocyclic Hadamard matrices and difference sets (2000)

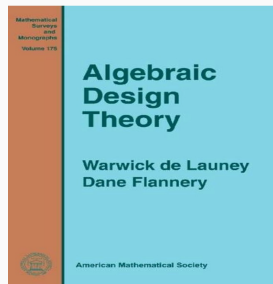
Structure of cocyclic Hadamard matrices of order $4p$

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- They showed that such matrices have indexing groups $K \times C_p$, where $|K| = 4$, and can be described by a set of block arrays.

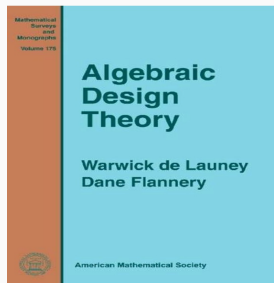


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- They showed that such matrices have indexing groups $K \times C_p$, where $|K| = 4$, and can be described by a set of block arrays.
- Every CHM of order $4p$ and $p > 3$ prime with indexing group $K \times C_p$ and cocycle ψ is equivalent to a matrix

$$\begin{bmatrix} W & X^a & Y^b & Z^{ab} \\ X & (-1)^r W^a & Z^b & (-1)^r Y^{ab} \\ Y & (-1)^t Z^a & (-1)^s W^b & (-1)^{s+t} X^{ab} \\ Z & (-1)^{r+t} Y^a & (-1)^s X^b & (-1)^{r+s+t} W^{ab} \end{bmatrix}$$

where $(r, s, t) \in \{(1, 0, 0), (0, 1, 0), (1, 1, 0), (1, 1, 1)\}$ depends on ψ , the blocks W, X, Y, Z are back-circulant, and a block M^x is circulant if and only if $x \in \{a, b, ab\} \subseteq K$ acts by inversion on C_p .[†]



[†]De Launey and Flannery: Algebraic Design Theory (2011)

Classification of cocyclic Hadamard matrices of order $4p$

- In 2019, Barrera Acevedo, Ó Catháin and Dietrich recovered the aforementioned 4×4 block arrays via a group theoretical approach.

Constructing cocyclic Hadamard matrices of order $4p$

Santiago Barrera Acevedo¹ | Padraig Ó Catháin² | Heiko Dietrich¹

¹School of Mathematics, Monash University, Clayton, Victoria, Australia

²Mathematical Sciences Department, Worcester Polytechnic Institute, Worcester, Massachusetts

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Santiago Barrera Acevedo, School of Mathematics, Monash University, Clayton, VIC 3800, Australia.
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- In 2019, Barrera Acevedo, Ó Catháin and Dietrich recovered the aforementioned 4×4 block arrays via a group theoretical approach.
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	p	3	5	7	11	13
# classes		1	1	3	63	336

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- They applied a construction algorithm to obtain the classification of CHMs of orders $4 \cdot 11$ and $4 \cdot 13$.
- They are currently exploring the idea of using SAT-solvers to classify CHMs of orders $4 \cdot 17$ and $4 \cdot 19$.

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It is natural to ask whether CHMs of orders $8p$ and $4pq$, for $2 < p < q$ primes, can be described by a set of block arrays, as in the case $4p$.

Cocyclic Hadamard matrices of order $8p$

- CHMs of order $8 \cdot 3$ are classified; there are 16 classes of such matrices[†].

[†] Ó Cathaín and Röder, The cocyclic Hadamard matrices of order less than 40 (2011)

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- $K \in \{C_2^3, C_4 \times C_2, D_8, Q_8\}$ (all polycyclic groups).

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Combining ideas of Ó Cathaín and Röder[†], and Barrera Acevedo et al[‡]. we have the following result.

Theorem

Let H be a CHM of order $8p$ with indexing group $G = K \times N$ and cocycle ψ . Then

$$H \equiv \left[\psi(k_i, k_j) \left[\phi \left(k_i k_j n^{k_j} m \right) \right]_{n, m \in N} \right]_{k_i, k_j \in K} \quad (5)$$

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For fixed k_i, k_j each inner $p \times p$ block $\left[\phi \left(k_i k_j n^{k_j} m \right) \right]_{n,m \in N}$ is group developed over N with respect to the action of K on N .

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Every matrix of form (5) is also cocyclic.

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K	Isomorphism type of \hat{K}	GAP ID [16, #]
$C_4 \times C_2$	$C_2 \times (C_4 \times C_2), C_4^2$ $C_2 \times C_8, C_2 \times C_8$ $C_2^2 \times C_4$	[16, 3], [16, 4] [16, 5], [16, 6] [16, 10]
C_2^3	$C_2 \times (C_4 \times C_2), D_8 \times C_2$ $C_2^4, Q_8 \times C_2$	[16, 3], [16, 11] [16, 14], [16, 12]
D_8	$C_2 \times (C_4 \times C_2), C_4^2$ D_{16}, SD_{16} $Q_{16}, D_8 \times C_2$	[16, 3], [16, 4] [16, 7], [16, 8] [16, 9], [16, 11]
Q_8	$C_4^2, Q_8 \times C_2$	[16, 4], [16, 12]

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C_2^3	$C_2 \times (C_4 \times C_2), D_8 \times C_2$ $C_2^4, Q_8 \times C_2$	[16, 3], [16, 11] [16, 14], [16, 12]
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Q_8	$C_4^2, Q_8 \times C_2$	[16, 4], [16, 12]

For each isomorphism type of \hat{K} we compute a representative cocycle.

Cocycles

Let $K = C_4 \times C_2$ and consider the presentation

$$K = \langle a, b, c \mid a^2 = 1, b^2 = c, c^2 = 1, b^a = b, c^a = c, c^b = c \rangle.$$

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The possible central extensions of K by C_2 are given by

$$\hat{K} = L_{i,k,r} = \langle a, b, c, z \mid a^2 = z^i, b^2 = c, c^2 = z^k, b^a = bz^r, z^2 = 1 \rangle$$

with $(i, k, r) \in \mathbb{Z}_2^3$.

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From the central extension $1 \rightarrow C_2 \xrightarrow{\iota} L_{i,k,r} \xrightarrow{\pi} K \rightarrow 1$ take a lift $l : K \rightarrow L_{i,k,r}$ and compute the 2-cocycle

$$\psi_{i,k,r}(u, v) = \iota^{-1}(l(u)l(v)l(uv)^{-1}). \quad (6)$$

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$$[\psi_{i,k,r}(u, v)]_{u,v \in K} =$$

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & (-1)^i & 1 & 1 & (-1)^i & (-1)^i & 1 & (-1)^i \\ 1 & (-1)^r & 1 & 1 & (-1)^r & (-1)^r & (-1)^k & (-1)^{k+r} \\ 1 & 1 & 1 & (-1)^k & 1 & (-1)^k & (-1)^k & (-1)^k \\ 1 & (-1)^{i+r} & 1 & 1 & (-1)^{i+r} & (-1)^{i+r} & (-1)^k & (-1)^{i+k+r} \\ 1 & (-1)^i & 1 & (-1)^k & (-1)^i & (-1)^{i+k} & (-1)^k & (-1)^{i+k} \\ 1 & (-1)^r & (-1)^k & (-1)^k & (-1)^{k+r} & (-1)^{k+r} & (-1)^k & (-1)^{k+r} \\ 1 & (-1)^{i+r} & (-1)^k & (-1)^k & (-1)^{i+k+r} & (-1)^{i+k+r} & (-1)^k & (-1)^{i+k+r} \end{bmatrix}.$$

There is a choice in the calculation of the cocycle $\psi_{i,k,r}$, but two cocycles from the same central extension differ by a coboundary.

Coboundaries

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The elements in the group of coboundaries $B^2(C_4 \times C_2, C_2)$ are determined as follows:

$$C_{\alpha,\beta,\gamma,\delta,\varepsilon} = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & \gamma & \delta & \gamma & \delta & \beta\gamma\varepsilon & \gamma\beta\varepsilon \\ 1 & \gamma & \alpha & \beta & \alpha\gamma\delta & \gamma\delta\varepsilon & \alpha\beta & \alpha\gamma\varepsilon \\ 1 & \delta & \beta & 1 & \varepsilon & \delta & \beta & \varepsilon \\ 1 & \gamma & \alpha\gamma\delta & \varepsilon & \alpha & \beta\gamma\delta & \alpha\beta\gamma & \alpha\varepsilon \\ 1 & \delta & \gamma\delta\varepsilon & \delta & \beta\gamma\delta & 1 & \beta\gamma\delta & \gamma\delta\varepsilon \\ 1 & \beta\gamma\varepsilon & \alpha\beta & \beta & \alpha\beta\gamma & \beta\gamma\delta & \alpha & \alpha\beta\gamma\delta\varepsilon \\ 1 & \beta\gamma\varepsilon & \alpha\gamma\varepsilon & \varepsilon & \alpha\varepsilon & \gamma\delta\varepsilon & \alpha\beta\gamma\delta\varepsilon & \alpha \end{bmatrix},$$

where $\alpha, \beta, \gamma, \delta, \varepsilon \in \langle -1 \rangle$.

Block structure - Example

From the description

$$H \equiv \left[\psi(k_i, k_j) \left[\phi(k_i k_j n^{k_j} m) \right]_{n, m \in \mathbb{N}} \right]_{k_i, k_j \in K}.$$

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Every CHM with indexing group $G \equiv (C_4 \times C_2) \times C_p$ is equivalent to a matrix

$$\mathcal{H}_1(S, T, U, V, W, X, Y, Z)_{\alpha, \beta, \gamma, \delta, \varepsilon}^{a, b, c, i, k, r} =$$

$$\begin{bmatrix} S & T^a & U^b & V^c & W^{ab} & X^{ac} & Y^{bc} & Z^{abc} \\ T & (-1)^i S^a & W^b & X^c & (-1)^i U^{ab} & (-1)^i V^{ac} & Z^{bc} & (-1)^i Y^{abc} \\ U & (-1)^r W^a & V^b & Y^c & (-1)^r X^{ab} & (-1)^r Z^{ac} & (-1)^k S^{bc} & (-1)^{k+r} T^{abc} \\ V & X^a & Y^b & (-1)^k S^c & Z^{ab} & (-1)^k T^{ac} & (-1)^k U^{bc} & (-1)^k W^{abc} \\ W & (-1)^{i+r} U^a & X^b & Z^c & (-1)^{i+r} V^{ab} & (-1)^{i+r} Y^{ac} & (-1)^k T^{bc} & (-1)^{i+k+r} S^{abc} \\ X & (-1)^i V^a & Z^b & (-1)^k T^b & (-1)^i Y^{ab} & (-1)^{i+k} S^{ac} & (-1)^k W^{bc} & (-1)^{i+k} U^{abc} \\ Y & (-1)^r Z^a & (-1)^k S^b & (-1)^k U^b & (-1)^{k+r} T^{ab} & (-1)^{k+r} W^{ac} & (-1)^k V^{bc} & (-1)^{k+r} X^{abc} \\ Z & (-1)^{i+r} Y^a & (-1)^k T^b & (-1)^k W^b & (-1)^{i+k+r} S^{ab} & (-1)^{i+k+r} U^{ac} & (-1)^k X^{bc} & (-1)^{i+k+r} V^{abc} \end{bmatrix} \odot$$

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where $C_4 \times C_2 = \langle a, b, c \rangle$, $i, k, r \in \{0, 1\}$, $\alpha, \beta, \gamma, \delta, \varepsilon \in \langle -1 \rangle$, J_p denotes the all 1's matrix of size $p \times p$, and \otimes and \odot denote the Kronecker and Hadamard products of matrices, respectively.

Theorem

Every CHM H of order $8p$, with $p > 3$ prime, and indexing group $G = K \ltimes N$, where $|K| = 8$ and $N \cong C_p$, is equivalent to one of four block matrices:

$$H_1 = \mathcal{H}_1(S, T, U, V, W, X, Y, Z)_{\alpha, \beta, \gamma, \delta, \varepsilon}^{a, b, c, i, k, r} \quad \text{for } K = C_4 \times C_2$$

$$H_2 = \mathcal{H}_2(S, T, U, V, W, X, Y, Z)_{\alpha, \beta, \gamma, \delta}^{a, b, c, i, j, k, r, s, t} \quad \text{for } K = C_2^3$$

$$H_3 = \mathcal{H}_3(S, T, U, V, W, X, Y, Z)_{\alpha, \beta, \gamma, \delta, \varepsilon}^{a, b, c, i, j, k} \quad \text{for } K = D_8$$

$$H_4 = \mathcal{H}_4(S, T, U, V, W, X, Y, Z)_{\alpha, \beta, \gamma, \delta, \varepsilon}^{a, b, c, i, r} \quad \text{for } K = Q_8$$

where $(C_4 \times C_2) = \langle a, b, c \rangle$, $i, k, r \in \{0, 1\}$ and $\alpha, \beta, \gamma, \delta, \varepsilon \in \langle -1 \rangle$.

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- Establishing Hadamard equivalences that preserve the block structures.
- Controlling eigenvalues of the block matrices.

Coboundary space reduction

Can we get rid of coboundaries?

Hola

Coboundary space reduction

Can we get rid of coboundaries?

For example, let $G \equiv (C_2^3) \times C_p$.

$\mathcal{H}_2(S, T, U, V, W, X, Y, Z)_{\alpha, \beta, \gamma, \delta}^{a, b, c, i, j, k, r, s, t} =$

$$\begin{bmatrix} S & T^a & U^b & V^c & W^{ab} & X^{ac} & Y^{bc} & Z^{abc} \\ T & (-1)^i s^a & \alpha W^b & \beta X^c & (-1)^i \alpha U^{ab} & (-1)^i \beta V^{ac} & \delta Z^{bc} & (-1)^i \delta Y^{abc} \\ U & (-1)^r \alpha W^a & (-1)^j s^b & \gamma Y^c & (-1)^{j+r} \alpha T^{ab} & (-1)^r \alpha \beta \delta Z^{ac} & (-1)^j \gamma V^{bc} & (-1)^{j+r} \beta \gamma \delta X^{abc} \\ V & (-1)^s \beta X^a & (-1)^t \gamma Y^b & (-1)^k s^c & (-1)^{s+t} \alpha \gamma \delta Z^{ab} & (-1)^{k+s} \beta T^{ac} & (-1)^{k+t} \gamma U^{bc} & (-1)^{k+s+t} \alpha \gamma \delta W^{abc} \\ W & (-1)^{i+r} \alpha U^a & (-1)^j \alpha T^b & \alpha \gamma \delta Z^c & (-1)^{i+j+r} s^{ab} & (-1)^{i+r} \alpha \beta \gamma Y^{ac} & (-1)^j \alpha \beta \gamma X^{bc} & (-1)^{i+j+r} \alpha \gamma \delta V^{abc} \\ X & (-1)^{i+s} \beta V^a & (-1)^t \beta \gamma \delta Z^b & (-1)^k \beta T^c & (-1)^{i+s+t} \alpha \beta \gamma Y^{ab} & (-1)^{i+k+s} s^{ac} & (-1)^{k+t} \alpha \beta \gamma W^{bc} & (-1)^{m-j-r} \beta \gamma \delta U^{abc} \\ Y & (-1)^{r+s} \delta Z^a & (-1)^{j+t} \gamma V^b & (-1)^k \gamma U^c & (-1)^{m-i-k} \alpha \beta \gamma X^{ab} & (-1)^{k+r+s} \alpha \beta \gamma W^{ac} & (-1)^{j+k+t} s^{bc} & (-1)^{m-i} \delta T^{abc} \\ Z & (-1)^{i+r+s} \delta Y^a & (-1)^{j+t} \beta \gamma \delta X^b & (-1)^k \alpha \gamma \delta W^c & (-1)^{m-k} \alpha \gamma \delta V^{ab} & (-1)^{m-j-t} \beta \gamma \delta U^{ac} & (-1)^{j+k+t} \delta T^{bc} & (-1)^m s^{abc} \end{bmatrix}$$

Notes

Coboundary space reduction

Can we get rid of coboundaries?

For example, let $G \equiv (C_2^3) \times C_p$.

$$\mathcal{H}_2(S, T, U, V, W, X, Y, Z)_{\alpha, \beta, \gamma, \delta}^{a, b, c, i, j, k, r, s, t} \equiv$$

$$\begin{bmatrix} S & T^a & U^b & \gamma V^c & \alpha W^{ab} & \beta \gamma X^{ac} & Y^{bc} & \delta Z^{abc} \\ T & (-1)^i S^a & \alpha W^b & \beta \gamma X^c & (-1)^i U^{ab} & (-1)^i \gamma V^{ac} & \delta Z^{bc} & (-1)^i Y^{abc} \\ U & (-1)^r \alpha W^a & (-1)^j S^b & Y^c & (-1)^{j+r} T^{ab} & (-1)^r \delta Z^{ac} & (-1)^j \gamma V^{bc} & (-1)^{j+r} \beta \gamma X^{abc} \\ \gamma V & (-1)^s \beta \gamma X^a & (-1)^t Y^b & (-1)^k S^c & (-1)^{s+t} \delta Z^{ab} & (-1)^{k+s} T^{ac} & (-1)^{k+t} U^{bc} & (-1)^{k+s+t} \alpha W^{abc} \\ \alpha W & (-1)^{i+r} U^a & (-1)^j T^b & \delta Z^c & (-1)^{i+j+r} S^{ab} & (-1)^{i+r} Y^{ac} & (-1)^j \beta \gamma X^{bc} & (-1)^{i+j+r} \gamma V^{abc} \\ \beta \gamma X & (-1)^{i+s} \gamma V^a & (-1)^t \delta Z^b & (-1)^k T^c & (-1)^{i+s+t} Y^{ab} & (-1)^{i+k+s} S^{ac} & (-1)^{k+t} \alpha W^{bc} & (-1)^{m-j-r} U^{abc} \\ Y & (-1)^{r+s} \delta Z^a & (-1)^{j+t} \gamma V^b & (-1)^k U^c & (-1)^{m-i-k} \beta \gamma X^{ab} & (-1)^{k+r+s} \alpha W^{ac} & (-1)^{j+k+t} S^{bc} & (-1)^{m-i} T^{abc} \\ \delta Z & (-1)^{i+r+s} Y^a & (-1)^{j+t} \beta \gamma X^b & (-1)^k \alpha W^c & (-1)^{m-k} \gamma V^{ab} & (-1)^{m-j-t} U^{ac} & (-1)^{j+k+t} T^{bc} & (-1)^m S^{abc} \end{bmatrix}$$

Coboundary space reduction

Can we get rid of coboundaries?

For example, let $G \equiv (C_2^3) \times C_p$.

$$\mathcal{H}_2(S, T, U, V, W, X, Y, Z)_{\alpha, \beta, \gamma, \delta}^{a, b, c, i, j, k, r, s, t} \equiv$$

$$\begin{bmatrix} S & T^a & U^b & \gamma V^c & \alpha W^{ab} & \beta \gamma X^{ac} & Y^{bc} & \delta Z^{abc} \\ T & (-1)^i S^a & \alpha W^b & \beta \gamma X^c & (-1)^i U^{ab} & (-1)^i \gamma V^{ac} & \delta Z^{bc} & (-1)^i Y^{abc} \\ U & (-1)^r \alpha W^a & (-1)^j S^b & Y^c & (-1)^{j+r} T^{ab} & (-1)^r \delta Z^{ac} & (-1)^j \gamma V^{bc} & (-1)^{j+r} \beta \gamma X^{abc} \\ \gamma V & (-1)^s \beta \gamma X^a & (-1)^t Y^b & (-1)^k S^c & (-1)^{s+t} \delta Z^{ab} & (-1)^{k+s} T^{ac} & (-1)^{k+t} U^{bc} & (-1)^{k+s+t} \alpha W^{abc} \\ \alpha W & (-1)^{i+r} U^a & (-1)^j T^b & \delta Z^c & (-1)^{i+j+r} S^{ab} & (-1)^{i+r} Y^{ac} & (-1)^j \beta \gamma X^{bc} & (-1)^{i+j+r} \gamma V^{abc} \\ \beta \gamma X & (-1)^{i+s} \gamma V^a & (-1)^t \delta Z^b & (-1)^k T^c & (-1)^{i+s+t} Y^{ab} & (-1)^{i+k+s} S^{ac} & (-1)^{k+t} \alpha W^{bc} & (-1)^{m-j-r} U^{abc} \\ Y & (-1)^{r+s} \delta Z^a & (-1)^{j+t} \gamma V^b & (-1)^k U^c & (-1)^{m-i-k} \beta \gamma X^{ab} & (-1)^{k+r+s} \alpha W^{ac} & (-1)^{j+k+t} S^{bc} & (-1)^{m-i} T^{abc} \\ \delta Z & (-1)^{i+r+s} Y^a & (-1)^{j+t} \beta \gamma X^b & (-1)^k \alpha W^c & (-1)^{m-k} \gamma V^{ab} & (-1)^{m-j-t} U^{ac} & (-1)^{j+k+t} T^{bc} & (-1)^m S^{abc} \end{bmatrix}$$

Hence,

$$H_2 = \mathcal{H}_2(S, T, U, V, W, X, Y, Z)_{\alpha, \beta, \gamma, \delta}^{a, b, c, i, j, k, r, s, t} \equiv \mathcal{H}_2(S, T, U, \gamma V, \alpha W, \beta \gamma X, Y, \delta Z)_{1, 1, 1, 1}^{a, b, c, i, j, k, r, s, t}$$

Coboundary space reduction

Proposition

Let

$$H_1 = \mathcal{H}_1(S, T, U, V, W, X, Y, Z)_{\alpha, \beta, \gamma, \delta, \epsilon}^{a, b, c, i, k, r} \quad H_2 = \mathcal{H}_2(S, T, U, V, W, X, Y, Z)_{\alpha, \beta, \gamma, \delta}^{a, b, c, i, j, k, r, s, t}$$

$$H_3 = \mathcal{H}_3(S, T, U, V, W, X, Y, Z)_{\alpha, \beta, \gamma, \delta, \epsilon}^{a, b, c, i, j, k} \quad H_4 = \mathcal{H}_4(S, T, U, V, W, X, Y, Z)_{\alpha, \beta, \gamma, \delta, \epsilon}^{a, b, c, i, r}$$

Then

$$H_1 \equiv \mathcal{H}_1(S, T, U, \alpha V, \gamma W, \alpha \delta X, \alpha \beta Y, \alpha \gamma \epsilon Z)_{\mathbf{1,1,1,1,1}}^{a, b, c, i, k, r}$$

$$H_2 \equiv \mathcal{H}_2(S, T, U, \gamma V, \alpha W, \beta \gamma X, Y, \delta Z)_{\mathbf{1,1,1,1}}^{a, b, c, i, j, k, r, s, t}$$

$$H_3 \equiv \mathcal{H}_3(S, T, \beta \epsilon U, V, W, X, \epsilon \gamma Y, \delta Z)_{\alpha, \mathbf{1,1,1,1}}^{a, b, c, i, j, k}$$

$$H_4 \equiv \mathcal{H}_4(S, T, U, \alpha V, W, \beta X, \gamma Y, \delta Z)_{\mathbf{1,1,1,1}, \epsilon}^{a, b, c, i, r}$$

Coboundary space reduction

Proposition

Let

$$H_1 = \mathcal{H}_1(S, T, U, V, W, X, Y, Z)_{\alpha, \beta, \gamma, \delta, \epsilon}^{a, b, c, i, k, r} \quad H_2 = \mathcal{H}_2(S, T, U, V, W, X, Y, Z)_{\alpha, \beta, \gamma, \delta}^{a, b, c, i, j, k, r, s, t}$$

$$H_3 = \mathcal{H}_3(S, T, U, V, W, X, Y, Z)_{\alpha, \beta, \gamma, \delta, \epsilon}^{a, b, c, i, j, k} \quad H_4 = \mathcal{H}_4(S, T, U, V, W, X, Y, Z)_{\alpha, \beta, \gamma, \delta, \epsilon}^{a, b, c, i, r}$$

Then

$$H_1 \equiv \mathcal{H}_1(S, T, U, \alpha V, \gamma W, \alpha \delta X, \alpha \beta Y, \alpha \gamma \epsilon Z)_{1, 1, 1, 1, 1}^{a, b, c, i, k, r}$$

$$H_2 \equiv \mathcal{H}_2(S, T, U, \gamma V, \alpha W, \beta \gamma X, Y, \delta Z)_{1, 1, 1, 1}^{a, b, c, i, j, k, r, s, t}$$

$$H_3 \equiv \mathcal{H}_3(S, T, \beta \epsilon U, V, W, X, \epsilon \gamma Y, \delta Z)_{\alpha, 1, 1, 1, 1}^{a, b, c, i, j, k}$$

$$H_4 \equiv \mathcal{H}_4(S, T, U, \alpha V, W, \beta X, \gamma Y, \delta Z)_{1, 1, 1, 1, \epsilon}^{a, b, c, i, r}$$

In the following, let

$$H_1 = \mathcal{H}_1(S, T, U, V, W, X, Y, Z)_{1, 1, 1, 1, 1}^{a, b, c, i, k, r} \quad H_2 = \mathcal{H}_2(S, T, U, V, W, X, Y, Z)_{1, 1, 1, 1}^{a, b, c, i, j, k, r, s, t}$$

$$H_3 = \mathcal{H}_3(S, T, U, V, W, X, Y, Z)_{\alpha, 1, 1, 1, 1}^{a, b, c, i, j, k} \quad H_4 = \mathcal{H}_4(S, T, U, V, W, X, Y, Z)_{1, 1, 1, 1, \epsilon}^{a, b, c, i, r}$$

Coboundary space reduction

Proposition

Let

$$H_1 = \mathcal{H}_1(S, T, U, V, W, X, Y, Z)_{\alpha, \beta, \gamma, \delta, \epsilon}^{a, b, c, i, k, r} \quad H_2 = \mathcal{H}_2(S, T, U, V, W, X, Y, Z)_{\alpha, \beta, \gamma, \delta}^{a, b, c, i, j, k, r, s, t}$$
$$H_3 = \mathcal{H}_3(S, T, U, V, W, X, Y, Z)_{\alpha, \beta, \gamma, \delta, \epsilon}^{a, b, c, i, j, k} \quad H_4 = \mathcal{H}_4(S, T, U, V, W, X, Y, Z)_{\alpha, \beta, \gamma, \delta, \epsilon}^{a, b, c, i, r}$$

Then

$$H_1 \equiv \mathcal{H}_1(S, T, U, \alpha V, \gamma W, \alpha \delta X, \alpha \beta Y, \alpha \gamma \epsilon Z)_{1, 1, 1, 1, 1}^{a, b, c, i, k, r}$$
$$H_2 \equiv \mathcal{H}_2(S, T, U, \gamma V, \alpha W, \beta \gamma X, Y, \delta Z)_{1, 1, 1, 1}^{a, b, c, i, j, k, r, s, t}$$
$$H_3 \equiv \mathcal{H}_3(S, T, \beta \epsilon U, V, W, X, \epsilon \gamma Y, \delta Z)_{\alpha, 1, 1, 1, 1}^{a, b, c, i, j, k}$$
$$H_4 \equiv \mathcal{H}_4(S, T, U, \alpha V, W, \beta X, \gamma Y, \delta Z)_{1, 1, 1, 1, \epsilon}^{a, b, c, i, r}$$

In the following, let

$$H_1 = \mathcal{H}_1(S, T, U, V, W, X, Y, Z)_{\alpha}^{a, b, c, i, k, r} \quad H_2 = \mathcal{H}_2(S, T, U, V, W, X, Y, Z)_{\epsilon}^{a, b, c, i, j, k, r, s, t}$$
$$H_3 = \mathcal{H}_3(S, T, U, V, W, X, Y, Z)_{\alpha}^{a, b, c, i, j, k} \quad H_4 = \mathcal{H}_4(S, T, U, V, W, X, Y, Z)_{\epsilon}^{a, b, c, i, r}$$

Block-structure-preserving equivalences

Can we multiply rows/columns of H_1, \dots, H_4 by -1 preserving their block structure?

Block-structure-preserving equivalences

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$$H_1 = \mathcal{H}_1(S, T, U, V, W, X, Y, Z)^{a,b,c,i,k,r} =$$

$$\begin{bmatrix} S & T^a & U^b & V^c & W^{ab} & X^{ac} & Y^{bc} & Z^{abc} \\ T & (-1)^i S^a & W^b & X^c & (-1)^i U^{ab} & (-1)^i V^{ac} & Z^{bc} & (-1)^i Y^{abc} \\ U & (-1)^r W^a & V^b & Y^c & (-1)^r X^{ab} & (-1)^r Z^{ac} & (-1)^k S^{bc} & (-1)^{k+r} T^{abc} \\ V & X^a & Y^b & (-1)^k S^c & Z^{ab} & (-1)^k T^{ac} & (-1)^k U^{bc} & (-1)^k W^{abc} \\ W & (-1)^{i+r} U^a & X^b & Z^c & (-1)^{i+r} V^{ab} & (-1)^{i+r} Y^{ac} & (-1)^k T^{bc} & (-1)^{i+k+r} S^{abc} \\ X & (-1)^i V^a & Z^b & (-1)^k T^b & (-1)^i Y^{ab} & (-1)^{i+k} S^{ac} & (-1)^k W^{bc} & (-1)^{i+k} U^{abc} \\ Y & (-1)^r Z^a & (-1)^k S^b & (-1)^k U^b & (-1)^{k+r} T^{ab} & (-1)^{k+r} W^{ac} & (-1)^k V^{bc} & (-1)^{k+r} X^{abc} \\ Z & (-1)^{i+r} Y^a & (-1)^k T^b & (-1)^k W^b & (-1)^{i+k+r} S^{ab} & (-1)^{i+k+r} U^{ac} & (-1)^k X^{bc} & (-1)^{i+k+r} V^{abc} \end{bmatrix}$$

This

$$H_1 = -1 \cdot H_1(-S, T, U, -V, -W, X, Y, -Z)^{a,b,c,i,k,r}$$

Block-structure-preserving equivalences

Can we multiply rows/columns of H_1, \dots, H_4 by -1 preserving their block structure?

$$H_1 = \mathcal{H}_1(S, T, U, V, W, X, Y, Z)^{a,b,c,i,k,r} \equiv$$

$$\begin{bmatrix} -S & T^a & U^b & -V^c & -W^{ab} & X^{ac} & Y^{bc} & -Z^{abc} \\ -T & (-1)^i S^a & W^b & -X^c & -(-1)^i U^{ab} & (-1)^i V^{ac} & Z^{bc} & -(-1)^i Y^{abc} \\ -U & (-1)^r W^a & V^b & -Y^c & -(-1)^r X^{ab} & (-1)^r Z^{ac} & (-1)^k S^{bc} & -(-1)^{k+r} T^{abc} \\ -V & X^a & Y^b & -(-1)^k S^c & -Z^{ab} & (-1)^k T^{ac} & (-1)^k U^{bc} & -(-1)^k W^{abc} \\ -W & (-1)^{i+r} U^a & X^b & -Z^c & -(-1)^{i+r} V^{ab} & (-1)^{i+r} Y^{ac} & (-1)^k T^{bc} & -(-1)^{i+k+r} S^{abc} \\ -X & (-1)^i V^a & Z^b & -(-1)^k T^b & -(-1)^i Y^{ab} & (-1)^{i+k} S^{ac} & (-1)^k W^{bc} & -(-1)^{i+k} U^{abc} \\ -Y & (-1)^r Z^a & (-1)^k S^b & -(-1)^k U^b & -(-1)^{k+r} T^{ab} & (-1)^{k+r} W^{ac} & (-1)^k V^{bc} & -(-1)^{k+r} X^{abc} \\ -Z & (-1)^{i+r} Y^a & (-1)^k T^b & -(-1)^k W^b & -(-1)^{i+k+r} S^{ab} & (-1)^{i+k+r} U^{ac} & (-1)^k X^{bc} & -(-1)^{i+k+r} V^{abc} \end{bmatrix}$$

Thus

$$H_1 = \mathcal{H}_1(S, T, U, V, W, X, Y, Z)^{a,b,c,i,k,r}$$

Block-structure-preserving equivalences

Can we multiply rows/columns of H_1, \dots, H_4 by -1 preserving their block structure?

$$H_1 = \mathcal{H}_1(S, T, U, V, W, X, Y, Z)^{a,b,c,i,k,r} \equiv$$

$$\begin{bmatrix} -S & T^a & U^b & -V^c & -W^{ab} & X^{ac} & Y^{bc} & -Z^{abc} \\ T & -(-1)^i S^a & -W^b & X^c & (-1)^i U^{ab} & -(-1)^i V^{ac} & -Z^{bc} & (-1)^i Y^{abc} \\ U & -(-1)^r W^a & -V^b & Y^c & (-1)^r X^{ab} & -(-1)^r Z^{ac} & -(-1)^k S^{bc} & (-1)^{k+r} T^{abc} \\ -V & X^a & Y^b & -(-1)^k S^c & -Z^{ab} & (-1)^k T^{ac} & (-1)^k U^{bc} & -(-1)^k W^{abc} \\ -W & (-1)^{i+r} U^a & X^b & -Z^c & -(-1)^{i+r} V^{ab} & (-1)^{i+r} Y^{ac} & (-1)^k T^{bc} & -(-1)^{i+k+r} S^{abc} \\ X & -(-1)^i V^a & -Z^b & (-1)^k T^b & (-1)^i Y^{ab} & -(-1)^{i+k} S^{ac} & -(-1)^k W^{bc} & (-1)^{i+k} U^{abc} \\ Y & -(-1)^r Z^a & -(-1)^k S^b & (-1)^k U^b & (-1)^{k+r} T^{ab} & -(-1)^{k+r} W^{ac} & -(-1)^k V^{bc} & (-1)^{k+r} X^{abc} \\ -Z & (-1)^{i+r} Y^a & (-1)^k T^b & -(-1)^k W^b & -(-1)^{i+k+r} S^{ab} & (-1)^{i+k+r} U^{ac} & (-1)^k X^{bc} & -(-1)^{i+k+r} V^{abc} \end{bmatrix}$$

Block-structure-preserving equivalences

Can we multiply rows/columns of H_1, \dots, H_4 by -1 preserving their block structure?

$$H_1 = \mathcal{H}_1(S, T, U, V, W, X, Y, Z)^{a,b,c,i,k,r} \equiv$$

$$\begin{bmatrix} -S & T^a & U^b & -V^c & -W^{ab} & X^{ac} & Y^{bc} & -Z^{abc} \\ T & -(-1)^i S^a & -W^b & X^c & (-1)^i U^{ab} & -(-1)^i V^{ac} & -Z^{bc} & (-1)^i Y^{abc} \\ U & -(-1)^r W^a & -V^b & Y^c & (-1)^r X^{ab} & -(-1)^r Z^{ac} & -(-1)^k S^{bc} & (-1)^{k+r} T^{abc} \\ -V & X^a & Y^b & -(-1)^k S^c & -Z^{ab} & (-1)^k T^{ac} & (-1)^k U^{bc} & -(-1)^k W^{abc} \\ -W & (-1)^{i+r} U^a & X^b & -Z^c & -(-1)^{i+r} V^{ab} & (-1)^{i+r} Y^{ac} & (-1)^k T^{bc} & -(-1)^{i+k+r} S^{abc} \\ X & -(-1)^i V^a & -Z^b & (-1)^k T^b & (-1)^i Y^{ab} & -(-1)^{i+k} S^{ac} & -(-1)^k W^{bc} & (-1)^{i+k} U^{abc} \\ Y & -(-1)^r Z^a & -(-1)^k S^b & (-1)^k U^b & (-1)^{k+r} T^{ab} & -(-1)^{k+r} W^{ac} & -(-1)^k V^{bc} & (-1)^{k+r} X^{abc} \\ -Z & (-1)^{i+r} Y^a & (-1)^k T^b & -(-1)^k W^b & -(-1)^{i+k+r} S^{ab} & (-1)^{i+k+r} U^{ac} & (-1)^k X^{bc} & -(-1)^{i+k+r} V^{abc} \end{bmatrix}$$

Thus,

$$H_1 \equiv \mathcal{H}_1(-S, T, U, -V, -W, X, Y, -Z)^{a,b,c,i,k,r}$$

Block-structure-preserving equivalences

Proposition

$$H_1 \equiv \pm 1 \mathcal{H}_1(-S, T, U, -V, -W, X, Y, -Z)^{a,b,c,i,k,r}$$

$$H_3 \equiv \pm 1 \mathcal{H}_3(-S, T, -U, -V, W, X, -Y, Z)_{\alpha}^{a,b,c,i,j,k,r,s,t}$$

$$\begin{aligned} H_4 &\equiv \pm 1 \mathcal{H}_4(-T, -V, W, -X, Y, -S, Z, U)_{\varepsilon}^{a,b,c,i,r} \equiv \pm 1 \mathcal{H}_4(-T, V, -W, -X, Y, S, -Z, U)_{\varepsilon}^{a,b,c,i,r} \\ &\equiv \pm 1 \mathcal{H}_4(-T, V, W, -X, -Y, S, Z, -U)_{\varepsilon}^{a,b,c,i,r} \equiv \pm 1 \mathcal{H}_4(T, -V, -W, X, Y, -S, -Z, U)_{\varepsilon}^{a,b,c,i,r} \\ &\equiv \pm 1 \mathcal{H}_4(T, -V, W, X, -Y, -S, Z, -U)_{\varepsilon}^{a,b,c,i,r} \equiv \pm 1 \mathcal{H}_4(T, V, -W, X, -Y, S, -Z, -U)_{\varepsilon}^{a,b,c,i,r} \end{aligned}$$

$$H_2 \equiv \pm 1 \mathcal{H}_2(e_1 S, e_2 T, e_3 U, e_4 V, e_5 W, e_6 X, e_7 Y, e_8 Z)^{a,b,c,i,j,k,r,s,t}$$

where $e_l \in \{\pm 1\}$, for $l = 1, \dots, 8$, and exactly three of e_1, e_2, e_3, e_4 and one of e_5, e_6, e_7, e_8 are -1 .

Block-structure-preserving equivalences

Can we rearrange the blocks of H_1, \dots, H_4 preserving their structure?

Thus

$$H_1 \equiv H_1(T, S, W, X, U, V, Z, Y)^{T^*S^*W^*X^*U^*V^*Z^*Y^*}$$

Block-structure-preserving equivalences

Can we rearrange the blocks of H_1, \dots, H_4 preserving their structure?

$$H_1 = \mathcal{H}_1(S, T, U, V, W, X, Y, Z)^{a,b,c,i,k,r} =$$

$$\begin{bmatrix} S & T^a & U^b & V^c & W^{ab} & X^{ac} & Y^{bc} & Z^{abc} \\ T & (-1)^i S^a & W^b & X^c & (-1)^i U^{ab} & (-1)^i V^{ac} & Z^{bc} & (-1)^i Y^{abc} \\ U & (-1)^r W^a & V^b & Y^c & (-1)^r X^{ab} & (-1)^r Z^{ac} & (-1)^k S^{bc} & (-1)^{k+r} T^{abc} \\ V & X^a & Y^b & (-1)^k S^c & Z^{ab} & (-1)^k T^{ac} & (-1)^k U^{bc} & (-1)^k W^{abc} \\ W & (-1)^{i+r} U^a & X^b & Z^c & (-1)^{i+r} V^{ab} & (-1)^{i+r} Y^{ac} & (-1)^k T^{bc} & (-1)^{i+k+r} S^{abc} \\ X & (-1)^i V^a & Z^b & (-1)^k T^b & (-1)^i Y^{ab} & (-1)^{i+k} S^{ac} & (-1)^k W^{bc} & (-1)^{i+k} U^{abc} \\ Y & (-1)^r Z^a & (-1)^k S^b & (-1)^k U^b & (-1)^{k+r} T^{ab} & (-1)^{k+r} W^{ac} & (-1)^k V^{bc} & (-1)^{k+r} X^{abc} \\ Z & (-1)^{i+r} Y^a & (-1)^k T^b & (-1)^k W^b & (-1)^{i+k+r} S^{ab} & (-1)^{i+k+r} U^{ac} & (-1)^k X^{bc} & (-1)^{i+k+r} V^{abc} \end{bmatrix}$$

Thus

$$H_1 = \mathcal{H}_1(T, S, W, X, U, V, Z, Y)^{a,b,c,i,k,r}$$

Block-structure-preserving equivalences

Can we rearrange the blocks of H_1, \dots, H_4 preserving their structure?

$$H_1 = \mathcal{H}_1(S, T, U, V, W, X, Y, Z)^{a,b,c,i,k,r} \equiv$$

$$\begin{bmatrix} S & T^a & U^b & V^c & W^{ab} & X^{ac} & Y^{bc} & Z^{abc} \\ T & (-1)^i S^a & W^b & X^c & (-1)^i U^{ab} & (-1)^i V^{ac} & Z^{bc} & (-1)^i Y^{abc} \\ U & (-1)^r W^a & V^b & Y^c & (-1)^r X^{ab} & (-1)^r Z^{ac} & (-1)^k S^{bc} & (-1)^{k+r} T^{abc} \\ V & X^a & Y^b & (-1)^k S^c & Z^{ab} & (-1)^k T^{ac} & (-1)^k U^{bc} & (-1)^k W^{abc} \\ W & (-1)^{i+r} U^a & X^b & Z^c & (-1)^{i+r} V^{ab} & (-1)^{i+r} Y^{ac} & (-1)^k T^{bc} & (-1)^{i+k+r} S^{abc} \\ X & (-1)^i V^a & Z^b & (-1)^k T^b & (-1)^i Y^{ab} & (-1)^{i+k} S^{ac} & (-1)^k W^{bc} & (-1)^{i+k} U^{abc} \\ Y & (-1)^r Z^a & (-1)^k S^b & (-1)^k U^b & (-1)^{k+r} T^{ab} & (-1)^{k+r} W^{ac} & (-1)^k V^{bc} & (-1)^{k+r} X^{abc} \\ Z & (-1)^{i+r} Y^a & (-1)^k T^b & (-1)^k W^b & (-1)^{i+k+r} S^{ab} & (-1)^{i+k+r} U^{ac} & (-1)^k X^{bc} & (-1)^{i+k+r} V^{abc} \end{bmatrix}$$

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Thus

$$H_1 \equiv \mathcal{H}_1(T, S, W, X, U, V, Z, Y)^{a,b,c,i,k,r}$$

Block-structure-preserving equivalences

Proposition

$$H_1 \equiv \mathcal{H}_1(T, S, W, X, U, V, Z, Y)^{a,b,c,i,k,r}$$

$$\begin{aligned} H_2 &\equiv \mathcal{H}_2(T, S, U, V, W, X, Y, Z)^{a,b,c,i,j,k,r,s,t} \equiv \mathcal{H}_2(U, W, V, Y, X, Z, S, T)^{a,b,c,i,j,k,r,s,t} \\ &\equiv \mathcal{H}_2(V, X, Y, S, Z, T, U, W)^{a,b,c,i,j,k,r,s,t} \equiv \mathcal{H}_2(W, X, Z, T, Y, S, W, U)^{a,b,c,i,j,k,r,s,t} \\ &\equiv \mathcal{H}_2(X, V, Z, T, Y, S, W, U)^{a,b,c,i,j,k,r,s,t} \equiv \mathcal{H}_2(Y, Z, S, U, T, W, V, X)^{a,b,c,i,j,k,r,s,t} \\ &\equiv \mathcal{H}_2(Z, Y, T, W, S, U, X, V)^{a,b,c,i,j,k,r,s,t} \end{aligned}$$

$$H_3 \equiv \mathcal{H}_3(T, S, W, X, U, V, Z, Y)_{\alpha}^{a,b,c,i,j,k,r,s,t}$$

$$\begin{aligned} H_4 &\equiv \mathcal{H}_4(T, V, W, X, Y, S, Z, U)_{\varepsilon}^{a,b,c,i,r} \equiv \mathcal{H}_4(U, Z, V, Y, T, W, S, X)_{\varepsilon}^{a,b,c,i,r} \\ &\equiv \mathcal{H}_4(V, X, Y, S, Z, T, U, W)_{\varepsilon}^{a,b,c,i,r} \equiv \mathcal{H}_4(W, U, X, Z, V, Y, T, S)_{\varepsilon}^{a,b,c,i,r} \\ &\equiv \mathcal{H}_4(X, S, Z, T, U, V, W, Y)_{\varepsilon}^{a,b,c,i,r} \equiv \mathcal{H}_4(Y, W, S, U, X, Z, V, T)_{\varepsilon}^{a,b,c,i,r} \\ &\equiv \mathcal{H}_4(Z, Y, T, W, S, U, X, V)_{\varepsilon}^{a,b,c,i,r} \end{aligned}$$

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with $(i, r) \in \{(0, 1), (1, 0), (1, 1)\}$.

Block-structure-preserving equivalences

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There are more block-structure-preserving equivalences arising from the specialisation of the “actions” a, b, c , and the parameters i, j, k, r, s, t and α, ε .

Control of eigenvalues

Recall

$$H_1 = \mathcal{H}_1(S, T, U, V, W, X, Y, Z)^{a,b,c,i,k,r} \quad H_2 = \mathcal{H}_2(S, T, U, V, W, X, Y, Z)^{a,b,c,i,j,k,r,s,t}$$

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From the equation

$$H_i H_i^T = 8pl_{8p},$$

for $i = 1, 2, 3, 4$, it follows that

$$SS^T + \dots + ZZ^T = 8pl_p.$$

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The gramians SS^T, \dots, ZZ^T are symmetric and circulant, and hence polynomials in the permutation matrix P of the p -cycle $(1, 2, \dots, p)$.

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The gramians SS^T, \dots, ZZ^T commute in pairs and are simultaneously diagonalisable.

Control of eigenvalues

For $i = 1, \dots, 8$ and $R \in \{S, \dots, Z\}$, let

$$\lambda_{i,R}$$

denote the i -th eigenvalue of RR^T .

If $A \subset \{S, \dots, Z\}$ then for $i = 1, \dots, 8$ we have

$$\sum_{R \in A} \lambda_{i,R} \leq 8p. \tag{7}$$

These inequalities can help to trim the search spaces significantly.

Algorithm

This algorithm describes a method to classify all CHMs H_1, H_2, H_3, H_4 of order $8p$ with $p > 3$ prime up to equivalence.

Let s, \dots, z the sums of the first rows of the blocks S, \dots, Z , respectively.

Input: a prime $p > 3$

Output: a list of all CHMs of order $8p$, up to equivalence

- 1: initialise L as an empty list
- 2: determine all decompositions $\mathcal{D} = \{(s, \dots, z) \in \mathbb{Z}^8 \mid s^2 + \dots + z^2 = 8p\}$
- 3: discard the element of \mathcal{D} that produce equivalent matrices
- 4: **for** $(s, \dots, z) \in \mathcal{D}$ **do**
- 5: construct \mathcal{S} as the set of back-circulant matrices over ± 1 of order p with row
- 6: sum s (that satisfy the eigenvalue constraint)
- 7: similarly, construct $\mathcal{T}, \mathcal{U}, \mathcal{V}, \mathcal{W}, \mathcal{X}, \mathcal{Y}, \mathcal{Z}$.
- 8: **for** $(S, \dots, Z) \in \mathcal{S} \times \dots \times \mathcal{Z}$ satisfying the eigenvalue constraints **do**
- 9: construct H_1, H_2, H_3, H_4 .
- 10: **if** H_i is Hadamard and $H \notin L$ up to equivalence **then** add H_i to L .
- 11: **return** L .
- 12:

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- 12: **print** Thank you!